# Lecture 23: Neural Networks and Pretraining 

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## Neural Networks

## Motivation

Recall linear regression / classification setup:

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\begin{aligned}
& L(\beta)=\frac{1}{n} \sum_{i=1}^{n}\left(y^{(i)}-\beta^{\top} x^{(i)}\right)^{2} \text { (linear) } \\
& L(\beta)=\frac{1}{n} \sum_{i=1}^{n}-\log \sigma\left((-1)^{y^{(i)}} \beta^{\top} x^{(i)}\right) \text { (logistic) }
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(E.g. true function not linear in $x$ )

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## Non-linear Examples




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- This gets tedious.
- What if we can't think of good features ahead of time?


## Non-parametric modeling

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- Random features
- Neural networks
- Kernels
- Decision trees


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Focus on first two for this lecture

## Random features

Input $x \in \mathbb{R}^{d}$, but can't think of good features function $\phi(x)$

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Solution: make $\phi$ random but high-dimensional:

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\begin{equation*}
\phi(x)=\operatorname{sign}(M x+b) \tag{1}
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where $M \in \mathbb{R}^{d \times k}$ and $b \in \mathbb{R}^{k}$ are random vectors (chosen once at beginning).

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Other features work too, e.g. $\cos (M x+b)$, etc. Key points are randomness (good variation) and high dimensionality (usually $k>d$ ).

- Will show later this is (approximately) equivalent to kernel regression!


## Random features: Jupyter demo

[switch to notebook]

## Learned features

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Two-layer neural network:

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\phi(x) & =\sigma\left(M_{1} x+b_{1}\right), \\
p(y \mid x) & =\sigma\left(M_{2} \sigma\left(M_{1} x+b_{1}\right)+b_{2}\right) .
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Modern ML: iterate to many layers (and use different non-linearity $\sigma$, convolutional structure, etc.)

## Learned features: Jupyter demo

[switch to notebook]

## Fitting a neural network model

How do we actually fit $M$ and $b$ ?

Recall stochastic gradient descent: update parameters $w=\left(M_{1}, M_{2}, b_{1}, b_{2}\right)$ by following gradient of the loss $\nabla L(w)$ :

$$
w^{\prime} \leftarrow w-\eta \nabla L(w)
$$

How do we compute $\nabla L(w)$ ?

## Computing the gradient

[on board]

## Backpropagation and autodiffentiation

- Given any "computation graph", we can write down derivatives recursively using the chain rule
- Then solve using dynamic programming!
- This is called backpropagation or autodifferentiation, key idea in Pytorch and other libraries


## Backprop in pytorch

## [Jupyter demo]

## Pre-training

## Motivation

- Suppose we want to train a classifier to predict the political slant of news
- Common situation:
- Lots of unlabeled data (all text on internet)
- Few labeled data (hand-label 1000 random articles)
- New instances might be OOD (news changes over time)
- How do we handle all the unlabeled data?
- First pretrain on very large amount of (possibly unlabeled) data
- Then finetune on smaller amount of labeled, task-specific data


## Pre-training: Examples

- Images: pretrain to predict Instagram tags (3.5B images), fine-tune on ImageNet (1M images)
- Images: pretrain on ImageNet (1M images), fine-tune on CIFAR-10 (50K images)
- Text: pretrain on Wikipedia (2.5B words) + BookCorpus ( 0.8 B words), fine-tune on [sentiment classification, entailment, etc.]

Largest language models pretrained on over 400B tokens!

## Pre-training: Details

[on board]

## Accuracy and Robustness





## Zero-shot Learning

The three settings we explore for in-context learning
Zero-shot
The model predicts the answer given only a natural language description of the task. No gradient updates are performed.

Translate English to French: | task description |
| :--- |
| cheese -> |

## One-shot

In addition to the task description, the model sees a single example of the task. No gradient updates are performed.

```
Translate English to French:
sea otter => loutre de wer
cheese =>
```

task description
example
prompt

## Few-shot

In addition to the task description, the model sees a few examples of the task. No gradient updates are performed.

| Translate English to French: | task deseription |
| :---: | :---: |
| sea otter $\Rightarrow$ loutre de ner | examples |
| peppermint $=$ menthe poivree |  |
| plush girafe $=$ g girafe peluche |  |
| cheese => | prompt |

Traditional fine-tuning (not used for GPT-3)
Fine-tuning
The model is trained via repeated gradient updates using a large corpus of example tasks.


## Few-shot Accuracy (I)



## Few-shot Accuracy (II)





Figure 8: GPT-3's confidence is a poor estimator of its accuracy and can be off by up to $24 \%$.

